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PPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO	
09/940,363	08/27/2001	Thomas A. Saksa	10011180-1	5070	
7590 03/25/2004			EXAMINER		
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			2859		

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Please find below and/or attached an Office communication concerning this application or proceeding.

	Application No.	Applicant(s)			
	09/940,363	SAKSA, THOMAS A.			
Office Action Summary	Examiner	Art Unit			
	Amy R Cohen	2859			
The MAILING DATE of this communication ap Period for Reply	pears on the cover sheet w	ith the correspondence address			
A SHORTENED STATUTORY PERIOD FOR REPL THE MAILING DATE OF THIS COMMUNICATION. - Extensions of time may be available under the provisions of 37 CFR 1. after SIX (6) MONTHS from the mailing date of this communication. - If the period for reply specified above is less than thirty (30) days, a replaced in the second of the s	136(a). In no event, however, may a rolly within the statutory minimum of third will apply and will expire SIX (6) MON te, cause the application to become AE	reply be timely filed ty (30) days will be considered timely. ITHS from the mailing date of this communication. BANDONED (35 U.S.C. § 133).			
Status					
1) Responsive to communication(s) filed on Ame	endment and RCE 23 Febr	uary 2004.			
<u> </u>					
3) Since this application is in condition for allows	Since this application is in condition for allowance except for formal matters, prosecution as to the merits is closed in accordance with the practice under <i>Ex parte Quayle</i> , 1935 C.D. 11, 453 O.G. 213.				
Disposition of Claims					
4)	awn from consideration. e rejected.				
Application Papers					
9) ☐ The specification is objected to by the Examination 10) ☑ The drawing(s) filed on 18 November 2002 is Applicant may not request that any objection to the Replacement drawing sheet(s) including the correct 11) ☐ The oath or declaration is objected to by the Examination is objected to be a considered to be a c	are: a)⊠ accepted or b)□ e drawing(s) be held in abeyar ction is required if the drawing	nce. See 37 CFR 1.85(a). (s) is objected to. See 37 CFR 1.121(d).			
Priority under 35 U.S.C. § 119					
12) Acknowledgment is made of a claim for foreign a) All b) Some * c) None of: 1. Certified copies of the priority documer 2. Certified copies of the priority documer 3. Copies of the certified copies of the pri application from the International Bures * See the attached detailed Office action for a list	nts have been received. Ints have been received in A Onity documents have been au (PCT Rule 17.2(a)).	Application No received in this National Stage			
Attachment(s) 1) Notice of References Cited (PTO-892) 2) Notice of Draftsperson's Patent Drawing Review (PTO-948) 3) Information Disclosure Statement(s) (PTO-1449 or PTO/SB/08 Paper No(s)/Mail Date	Paper No(Summary (PTO-413) s)/Mail Date Informal Patent Application (PTO-152)			

Art Unit: 2859

DETAILED ACTION

Claim Rejections - 35 USC § 103

- 1. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
 - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.
- 2. Claims 1, 2, 4-9, 12, 13, 22, 23, 27-35 are rejected under 35 U.S.C. 103(a) as being unpatentable over Wiklof et al. (U. S. Patent No. 5,825,995) in view of Coulter et al. (U. S. Patent No. 4,233,749).

Wiklof et al. discloses a measurement and marking device, comprising: a housing (102); a position sensing assembly (126) mounted in the housing and adapted to sense a position of the housing relative to an object (141) as the housing is moved along a surface of the object (Col 6, lines 6-42); a printhead assembly (110) mounted in the housing and adapted to print (112) on the surface of the object as the housing is moved along the surface of the object (Col 3, lines 55-63); a controller (124) mounted in the housing and communicating with the positional sensing assembly and the printhead assembly, wherein the controller is adapted to operate the printhead assembly to print a mark on the surface of the object based on the position of the housing relative to the object as the housing is moved along the surface of the object (Col 4, lines 28-45), a user interface (128) mounted on the housing and communicating with the controller (Figs. 1-2), the user interface including an input configured for operation by a user (Col 4, lines 28-44 and Col 5, lines 50-57), wherein the housing has a first side (114) adapted to be oriented substantially parallel with the surface of the object as the housing is moved along the surface of the object and

Art Unit: 2859

includes a first opening (150) formed in the first side and a second opening (113) formed in the first side, wherein the positional sensing assembly communicates with the first side of the housing through the first opening and the printhead assembly communicates with the first side of the housing through the second opening (Fig. 1).

Wiklof et al. discloses the measurement and marking device whereon the controller is adapted to operate the printhead assembly to print a plurality of markings on the surface of the object at predetermined intervals as the housing is moved along the surface of the object (Col 3, line 64-Col 2, line 13).

Wiklof et al. discloses the measurement and marking device wherein the plurality of markings represent on of standard measurement and scaled measurements (Col 13, lines 21-56).

Wiklof et al. discloses the measurement and marking device wherein the printhead assembly is adapted to print at least one of graphics and text of a surface of the object as the housing is moved along the surface of the object (Col 1, lines 54-66 and Col 4, lines 45-65).

Wiklof et al. discloses the measurement and marking device wherein the position sensing assembly includes a wheel (116) rotatably mounted in the housing (Fig. 3), wherein the wheel is adapted to contact the surface of the object and rotate as the housing is moved along the surface of the object, and wherein the controller is adapted to determine the position of the housing relative to the object based on the rotation of the wheel (Col 6, lines 25-63).

Wiklof et al. discloses the measurement and marking device wherein the positional sensing assembly includes an optical sensor (163) mounted in the housing (Fig. 3), wherein the optical sensor is adapted to sense the surface of the object as the housing is moved along the surface of the object (Col 6, lines 25-63).

Art Unit: 2859

Wiklof et al. discloses a measurement and marking device wherein the printhead assembly includes a plurality of orifices formed in a front thereof (plurality of printing elements would have a plurality of orifices for the ink to come out), wherein the front face communicates with the first side of the housing (Col 4, lines 1-13).

Wiklof et al. discloses the measurement and marking device comprising a power supply (198) mounted in the housing (Col 7, lines 50-64) wherein the power supply supplies power to the measurement and marking device (Fig. 4).

Wiklof et al. discloses a method of transferring a measurement of a first object to a second object, the method comprising: moving a housing (102) along a surface of the first object (141), including orienting a first side (114) of the housing substantially parallel with the surface of the first object (Col 17, lines 19-36); sensing a position of the housing relative to the first object with a positional sensing assembly (126) mounted in the housing and communicating with the first side of the housing through a first opening (150) in the first side of the housing as the housing is moved along the surface of the first object; locating a feature of the first object, including recording the position of the housing at the feature of the first object (Col 17, line 19-Col 18, line 6); moving the housing along a surface of the second object, including orienting the first side of the housing substantially parallel with the surface of the second object (Col 17, lines 19-36 and Col 2, lines 8-29); sensing a position of the housing relative to the second object with the positional sensing assembly as the housing is moved along the surface of the second object (Col 17, line 19-Col 18, line 6 and Col 2, lines 8-29); and printing a mark representing the feature of the first object on the surface of the second object with a printhead assembly (110) mounting in the housing and communicating with the first side of the housing through a second

Art Unit: 2859

opening (113) in the first side of the housing when the position of the housing relative to the second object coincides with the position of the housing at the feature of the first object (Col 18,

lines 7-15 and Col 2, lines 8-29).

Wiklof et al. does not disclose a measurement and marking device and method of printing wherein the controller is adapted to store the position of the housing relative to the object as a measurement of the object when the input of the user interface is operated by the user; comprising receiving and storing a predetermined position for printing of the measurement marking at a controller within the housing.

Coulter et al. discloses a measurement and marking device (Fig. 1) wherein the controller (34) is adapted to store the position of the housing relative to the object as a measurement of the object when the input of the user interface is operated by the user (Col 2, lines 39-67).

Coulter et al. discloses the measurement and marking device wherein the positional sensing assembly is adapted to sense a position of the housing relative to a first object and measure a dimension of the first object as the housing is moved along a surface of the first object, wherein the positional sensing assembly is adapted to sense a position of the housing relative to a second object as the housing is moved along a surface of a second object, and wherein the controller is adapted to operate the printhead assembly to print the mark on the surface of the second object based on the dimension of the first object and the position of the housing relative to the second object as the housing is moved along the surface of the second object (Col 2, line 39-Col 3, line 48 and Col 5, line 11-Col 6, line 53).

Coulter et al. discloses the measurement and marking device wherein the controller is adapted to operate the printhead assembly to print the mark on the surface of the second object

Art Unit: 2859

based on the position of the housing relative to the first object when the input is operated by the user and the position of the housing relative to the second object as the housing is moved along a surface of the second object (Col 5, line 11-Col 6, line 53).

Coulter et al. discloses a method of transferring a measurement of a first object to a second object, the method comprising: receiving user input at a feature of the first object and storing the position of the housing at the feature of the first object as a measurement of the first object with a controller (34) mounted in the housing (Col 2, lines 39-67 and Col 5, line 11-Col 6, line 53).

Coulter et al. discloses the method wherein the step of sensing the position of the housing relative to the first object includes measuring a dimension of the first object, wherein locating the feature of the first object includes measuring at least one of a dimension to the feature of the first object and a dimension of the feature of the second object, and wherein printing the mark on the surface of the second object includes printing the mark on the surface of the second object when the position of the housing relative to the second object coincides with the at least one of the dimension to the feature of the first object and the dimension of the feature of the first object (Col 2, lines 39-67 and Col 5, line 11-Col 6, line 53).

Coulter et al. discloses a measurement and marking device and method wherein the positional sensing assembly is adapted to measure a dimension of a first object as the housing is moved along a surface of the first object, and wherein the controller is adapted to operate the printhead assembly to print the mark on a surface of a second object at predetermined intervals within the dimension of the first object as the housing is moved along the surface of the second object (Col 2, lines 39-67 and Col 5, line 11-Col 6, line 53).

Art Unit: 2859

It would have been obvious to one of ordinary skill in the art at the time the invention was made to modify the measurement and marking device of Wiklof et al. to be adapted to record the position of the housing relative to the object when the input of the user interface is operated by the user and receive and store a predetermined position for printing of the measurement marking, as taught by Coulter et al., so that the measurement and marking device would accurately print at preselected positions determined and inputted by the user (Coulter et al., Col 1, lines 40-53).

Response to Arguments

- 3. Regarding new claims 34 and 35: The subject matter claimed in claims 34 and 35 is already presented in claims 1 and 22, respectively, therefore, the rejections of claims 1 and 22 also include a rejection of claims 34 and 35.
- 4. Applicant's arguments filed 09 December 2003, and entered with the RCE filed 23 February 2004 have been fully considered but they are not persuasive.

Regarding Applicant's arguments that Wiklof et al. and Coulter et al. patents in combination do not teach or suggest a measurement and marking device wherein a controller is adapted to store a position of the housing relative to an object as a measurement of an object wherein an input of the user interface is operated by a user, nor a method of transferring a measurement of a first object to a second object, including receiving user input at a feature of the first object and storing the position of the housing at the feature of the first object as a measurement of the first object with the controller mounted in the housing (See Remarks, page 8, last paragraph), Examiner respectfully disagrees.

Art Unit: 2859

Wiklof et al. discloses a measurement and marking device wherein a controller is adapted to record a position of the housing relative to an object as a measurement of an object wherein an input of the user interface is operated by a user, and a method of transferring a measurement of a first object to a second object, including receiving user input at a feature of the first object and recording the position of the housing at the feature of the first object as a measurement of the first object with the controller mounted in the housing (Wiklof et al. Col 4, lines 28-44, specifically lines 36-44, and Col 17, line 19-Col 18, line 10 and Figs. 1 and 2). Coulter et al. discloses a measurement and marking device adapted to store data (Coulter et al. Col 2, lines 30-60). Therefore, the combination of Wiklof et al. and Coulter et al. would perform the functions as claimed by the applicant, including storing the data.

Conclusion

5. Any inquiry concerning this communication or earlier communications from the examiner should be directed to Amy R Cohen whose telephone number is (571) 272-2238. The examiner can normally be reached on 8 am - 5 pm, M-F.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Diego F. Gutierrez can be reached on (571) 272-2245. The fax phone number for the organization where this application or proceeding is assigned is 703-872-9306.

Art Unit: 2859

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free).

ARC March 19, 2004

> Diego Gutierrez Supervisory Examiner Tech Center 2800